TRANSFER LEARNING

Domain adaptation 0000

FINE TUNING

Target examples

IMPLEMENTATION 0000



TRANSFER LEARNING

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DOMAIN ADAPTATION

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LACK OF UNLABELED DATA

Can we do Deep Learning with few labeled data?

- Learn useful representation from unlabeled data
- Train on a nearby surrogate objective for which it is easier to generate labels



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LACK OF UNLABELED DATA

Can we do Deep Learning with few labeled data?

- Learn useful representation from unlabeled data
- Train on a nearby surrogate objective for which it is easier to generate labels
- Transfer learned representation from a related task



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Training a Deep net from scratch on your dataset can be hard



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Initial task/domain





Same domain





Same task

INTRODUCTION	
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TRANSFER LEARNING

Concept

- Several networks have already been trained on a different domain for a different source task
- Adapt this network to the target class

Many variations

- Close domain, different task
- Different domain, same task
- Partial/full adaptation

See Lecture

"CNN Architectures"

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Source: Pang & Yang, TKDE 2010)

We concentrate on domain adaptation/multi-task learning

DOMAIN ADAPTATION

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DOMAIN ADAPTATION

Domain adaptation

- Domains are modeled as probability distributions over an instance space
- Task associated to a domain (classification, regression..)

The question

How can we learn a low-error classifier on a target data distribution, using labeled data from a source distribution ?

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DOMAIN ADAPTATION

- $\mathcal{X}_S, \mathcal{X}_T$: source/target domain
- ▶ $\mathcal{Y}_S, \mathcal{Y}_T$: source/target label space

What can happen

- ▶ Data distribution change from \mathcal{X}_S to \mathcal{X}_T or $\mathbb{P}_S(x) \neq \mathbb{P}_T(x)$.
- Conditional probabilities may be different: $\mathcal{Y}_S \neq \mathcal{Y}_T$ or $\mathbb{P}_S(y|x) \neq \mathbb{P}_T(y|x)$



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Target examples

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Use output of one or more layers as feature detector



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NOT ONLY IN COMPUTER VISION



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It works well...

... But can we do better than off-the-shelf features ?

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It works well...

... But can we do better than off-the-shelf features ?

Fine tuning

- Change the classification layer to match the problem
- Retrain some/all layers of the whole network

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What layers to choose ?

- In computer vision
 - First layers detect simpler and more general patterns
 - Deeper layers capture more specific patterns related to data
- \Rightarrow Allow the last block(s) of convolution/pooling to be retrained.
- In sequential data: may keep the last few layers

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FINE TUNING

Freeze / Finetune

- Frozen layers: not updated during backpropagation
- Finetuned layers: updated during backpropagation
- Depends on the target task:
 - freeze if target task labels are scarce and no overfitting
 - finetune if more target labels.
- $\rightarrow\,$ set learning rates to be different for each layer to find a tradeoff





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FINE TUNING

- If sufficient examples are available, fine tuning improves generalization
- Transfer learning and fine tuning can serve as an initialization process
- Very often better performance than training from scratch



Yosinki et al, NIPS 2014 Source: 500 classes from ImageNet Target, another 500 classes from ImageNet.

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Target examples

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MULTITASK LEARNING

The multilayer architecture of Deep Neural Network makes them suitable for multitask learning.



Huang & al, ICASSP 2013.

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The training task can also depend on the number of training examples in the target domain.

- Sufficient number of examples : OK
- No examples: unsupervised domain adaptation
- Few number of examples (Few-shot learning)
 - Embedding learning
 - Data augmentation
 - Data generation
 - Semi supervised domain adaptation

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EMBEDDING LEARNING

Embedding learning: siamese, triplet network...



See lecture

Matching networks

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DATA AUGMENTATION

Given one example, generate n new ones using transformations (rotation, scaling, noise adding, nonlinear transformations, color processing...)



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DATA GENERATION

Model the data distribution into the target space in order to be able to generate new and unseen samples.

- Generative Adversarial Networks (GANs)
- Variational Autoencoders
- ▶ ...

See lecture

Generative models

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UN- OR SEMI-SUPERVISED DOMAIN ADAPTATION

- Matching source distributions
- Combination of fine tuning & unsupervised adaptation

Out of the scope of this lecture.

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TRAINABLE/NON TRAINABLE

$$y = \boldsymbol{W}^T \boldsymbol{x} + \boldsymbol{b}$$

dense = tt.keras.layers.Dense(7)
dense.build((None,5))
dense.traibable#False
print("veights:", tendense.weights))
print("veinable_weights:", lenidense.trainable_weights))
print("ronm_trainable_weights:", lenidense.nom_trainable_weights))
print(dense.weights)

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TRAINABLE/NON TRAINABLE

$$y = \boldsymbol{W}^T \boldsymbol{x} + \boldsymbol{b}$$

dense = tt.keras.layers.Dense(7)
dense.build([Non_5])
dense.trainable=false
print("veights:", len(dense.weights))
print("veights:", len(dense.trainable_weights))
print("non_trainable_weights:", len(dense.non_trainable_weights))
print(dense.weights)

weights: 2 restanble_weights: 8 restanble_weights: 8 restanble_weights: 8 restanble_weights: 9 restanble_weights: 9 restanble_weights: 8 restanble_weig

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IN KERAS



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IN KERAS

Transfer Learning + Fine tuning